

Reference Specifications

No: 01100028

K77 INCREMENTAL

Ver. 4. 0 Page 1/6



1. K77 Incremental Optical Encoder (Through hole)

1.1 Introduction:

K77 is an ultra-thin mechanical flexible connection design, the product is compact, highly integrated, easy to install, and can solve the user's high environmental requirements and installation problems in limited space.

1.2 Feature

- Encoder external diameter Ø77mm, thickness 31mm, diameter of shaft up to Ø30mm, achieve ultra-thin miniaturization
- Ring locking mounting structure
- · Adopt non-contact photoelectric principle
- Resolution up to 10000PPR

1.3 Application:

Motor, CNC and other industrial automation

1.4 Connection:

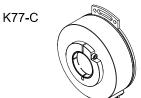
- Radial socket (M12 8pin male socket)
- Radial cable (standard length 1000mm)

1.5 Protection:

IP65

1.6 Weight:

About 400g

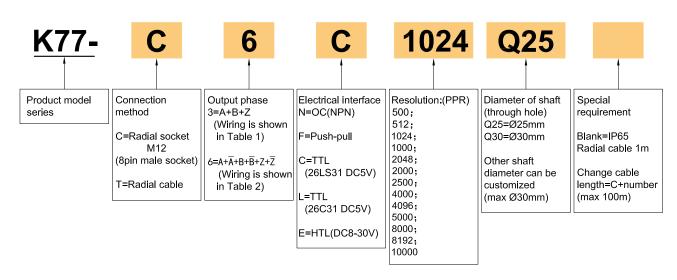


K77-T



Model Selection Guide

2.1 Model composition(select parameters)

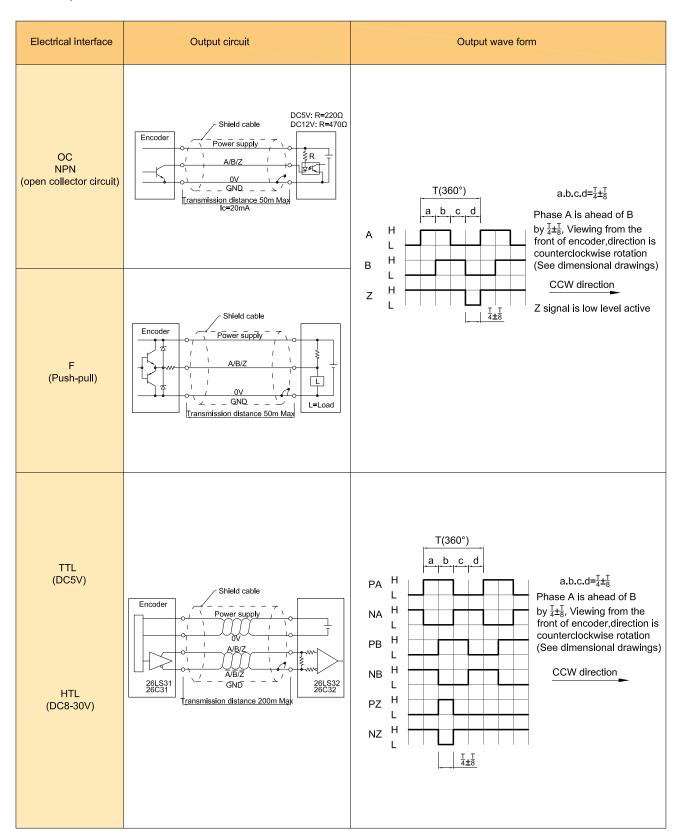


- 2.2 Please consult with sales for confirmation of customized products(Refer to parameters that are not in the model selection guide)
 - Shaft can be customized(Max Ø30mm)
 - Cable length can be customized(Standard product 1000mm)
 - Resolution can be customized(Max 65536PPR)
 - Installation size can be customized(Spring plate)

K77 INCREMENTAL

Ver. 4. 0 Page 2/6

3. Output Mode





No: 01100028

4. Electrical Characteristics

Parameter interface		lectrical terface	ОС	Push-pull	TTL	HTL	
Sup	Supply voltage		DC+5V±5%; DC8V-30V±5%		DC+5V±5%	DC8-30V±5%	
Cor	Consumption current		100mA Max		120mA Max		
Allo	Allowable ripple		≤3%rms				
Top	Top response frequency		100KHz		200KHz	300KHz	
	Output current	Input	≤30mA	≤30mA	- ≤±20mA	≤±50mA	
Output capacity		Output	_	≤10mA	SIZONIA		
	Output voltage	"H"	_	≥[(Supply voltage)-2.5V]	≥2.5V	≥Vcc-3 VDC	
utbut		"L"	≤0.4V	≤0.4V(30mA)	≤0.5V	≤1V VDC	
Ō	Load voltage		≤DC30V	_	_		
Rise	Rise & Fall time		Less than 2us(cable length: 2m)		Less than 1us (Cable length: 2m) ≤100ns		
Insu	Insulation strength		AC500V 60s				
	Insulation resistance		10ΜΩ				
Mar	Mark to space ratio		45% to 55%				
Phase shift between A & B			90°±10° (frequency in low speed)				
		В	90°±20° (frequency in high speed)				
Orig	Origin motion		Low level available —				
GND			not connect to encoder				

5. Mechanical Characteristics

Diameter of shaft	Ø25mm; Ø30mm(stainless steel)
Starting torque	Less than 80×10 ⁻³ N·m
Inertia moment	Less than 100×10 ⁻⁶ kg·m²
Shaft load	Radial 70N; Axial 50N
Slew speed	≤3000 rpm
Shell material	Aluminium alloy
Weight	about 400g

6. Environmental Specifications

Environmental temperature	Operating: -20~+85°C(repeatable winding cable: -10°C); Storage: -25~+90°C
Environmental humidity	Operating and storage: 35~85%RH(noncondensing)
Vibration(endure)	Amplitude 0.75mm,5~55Hz,2h for X,Y,Z direction individually
Shock(endure)	1960m/s²,11ms three times for X,Y,Z direction individually
Protection	IP50

Ver. 4. 0 Page 4/6



No: 01100028

7. Wiring table

7.1 Table 1

	Socket pin number (M12_8Pin male socket)		Wire color (cable connection)	Explanation
	1	Up	Red	Power supply Positive terminal
	2	Un	Black	Power supply negative terminal
5	3	А	White	A (one turn pulse signal)
6 0 04	4	-	-	Unallocated
70 03	5	В	Green	B (one turn pulse signal)
	6	-	-	Unallocated
	7	Z	Yellow	Z(zero signal)
	8	-	-	Unallocated
	GND	GND	GND	No encoder body connected

7.2 Table 2

	Socket pin number (M12 8Pin male socket)		Wire color (cable connection,Twisted pair)		Explanation	
	1	Up	Red		Power supply	
	2	Un	Black		Tower suppry	
5	3	А	White		А	
6 0 04	4	Ā	White/BK		(one turn pulse signal)	
70 08 03	5	В	Green		В	_
	6	B	Green/BK		(one turn pulse signal)	
	7	Z	Yellow		Z(zero signal)	
	8	Z	Yellow/BK			
	GND	GND	GND	GND	No encoder body connected	

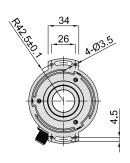
K77 PHISCREMENTAL

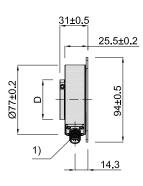
Ver. 4. 0 Page 5/6

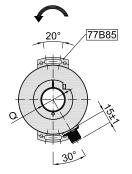


8. Basic Dimensions

8.1 K77-C(Radial socket connection)







 Q(diameter of shaft)
 D

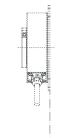
 Ø25^{G7}(^{+0.028}(+0.007)
 Ø44

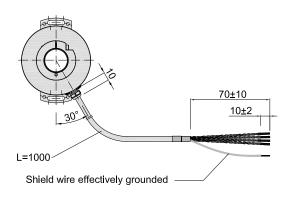
 Ø30^{G7}(^{+0.028}(+0.007)
 Ø46

This side is the front of the encoder

8.2 K77-T(Radial cable connection)



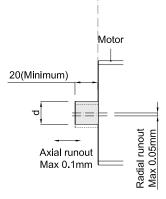


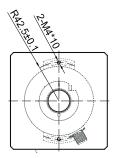


9. Assembly requirements



Mounting screws Inner hexagon bolt +flat washer Specification: M4*10 Material: stainless steel Quantity: 2





Unit: mm



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= Shaft rotation direction of the signal output

1) = M12 8Pin male socket

About vibration

Vibration act on encoder always cause wrong pulse, so we should pay attention to working place. More pulse per revolution, narrower groovy spacing of grating, more effect to encoder by vibration, when rev is low or stop, vibration act on shaft or main body would cause grating vibrating, so encoder might make wrong pulse.



10. Recommended Accessories

Plug and cable	Brief description	No.	Order No.
	C01=Connection type head A: M12, 8-pin female straight connector; Connection type head B: M12, 8-pin male straight connector; Cable length: 2M 8-core with shield,halogen-free PUR	K77C01	44400001
	C02=Connection type head A: M12, 8-pin female straight connector; Connection type head B: M12, 8-pin male straight connector; Cable length: 5M 8-core with shield,halogen-free PUR	K77C02	4440002
	C03=Connection type head A: M12, 8-pin female straight connector; Connection type head B: Bare wire end; Cable length: 1M 8-core with shield,halogen-free PUR	K77C03	44400003
	C04=Connection type head A: M12, 8-pin female straight connector; Connection type head B: Bare wire end; Cable length: 2M 8-core with shield,halogen-free PUR	K77C04	44400004
	C05=Connection type head A: M12, 8-pin female straight connector; Connection type head B: Bare wire end; Cable length: 5M 8-core with shield,halogen-free PUR	K77C05	44400005